

Computational helioseismology

How to get our hands on the interior of the Sun

Tilman Alemán, Damien Fournier, Laurent Gizon, Martin Halla, Thorsten Hohage, Christoph Lehrenfeld, Björn Müller, Janosch Preuß, Paul Stocker



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Institute for Numerical and Applied Mathematics



MAX PLANCK INSTITUTE
FOR SOLAR SYSTEM RESEARCH



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C04: Correlations of solar oscillations:
modeling and inversions

CRC 1456 Opening Symposium, March 17, 2022

Structure of the talk

Helioseismological data

- Observed data
- Preprocessed data

The forward solver

Input: excitations/parameters in the Sun

Task: compute velocity (on the surface)

- Interior PDE model and discretization
- Boundary conditions for the Sun

The inverse problem

Input: measurements on the surface

Task: compute excitation/parameters in the Sun

- Iterative holography (advertisement)



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More details?

↪ C04 poster presentation
(after plenary)



Helioseismological data

What is helioseismology?



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Oxford dictionary

“The study of the Sun’s **interior** by the observation and analysis of **oscillations** at its **surface**.”

global helioseismology

- input: frequencies of resonances (eigenmodes)
- yields radially symmetric (reference) model of the Sun

Aims:

- Space weather prediction
- Understanding the solar cycle

local helioseismology

- input: travel times / correlations of oscillations
- inverse boundary value problems, typically in the frequency domain
- 2D/3D imaging of Sun (farside/interior)

Observed data

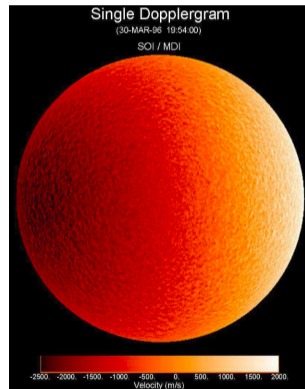
Dopplergrams from decades

Images of the **line-of-sight velocities** at the solar surface computed from **Doppler shifts** of certain (atomic) spectral lines.



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Location	Instrument	Time	Spatial resol.	temporal resol.
SDO satellite	HMI: Helioseismic & Magnetic Imager	05/2010 – now	4096 ²	45s
SOHO satellite	MDI: Michelson Doppler Imager	05/1996 – 04/2011	1024 ²	60s
GONG ground based	Fourier Tachometer	1995 – now	839 ²	60s



MDI image (from Gough¹)

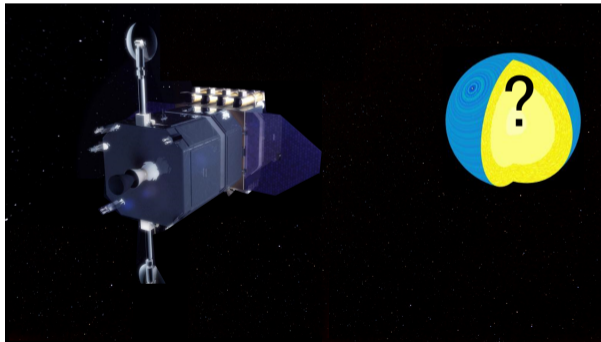
¹D. Gough, Vainu Bappu Memorial Lecture: What is a sunspot? 2010

Origin of oscillations



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- The outer 28% of the solar interior form the solar convection zone.
- Turbulence effectively acts as random perturbation.
- Waves propagate from here to the surface where they can be observed.





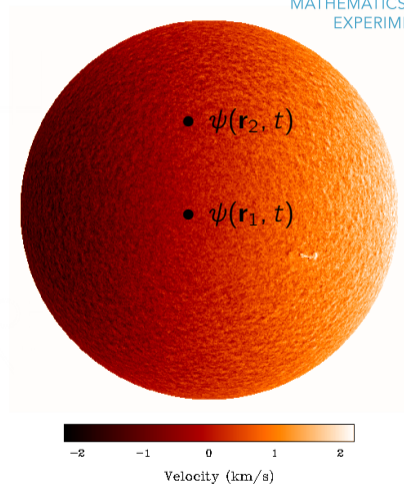
Preprocessed data

Correlations

- Consider line-of-sight velocities $\psi(\mathbf{r}_i, t)$ $i = 1, 2$.

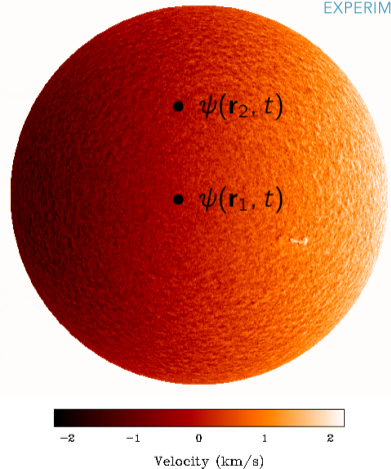
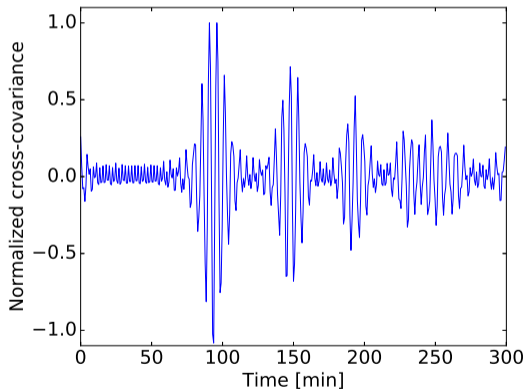


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Correlations

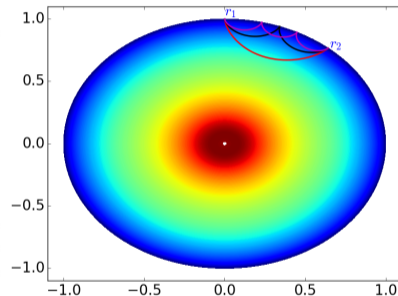
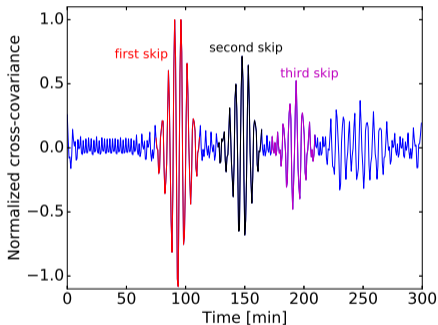
- Consider line-of-sight velocities $\psi(\mathbf{r}_i, t)$ $i = 1, 2$.
- Cross covariance between a point \mathbf{r}_1 at the equator and \mathbf{r}_2 at a latitude of 40° .



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Correlations

- Cross covariance between a point \mathbf{r}_1 at the equator and \mathbf{r}_2 at a latitude of 40° .



- Waves are refracted due to rapid sound speed increase

Correlation data



Cross-correlations in frequency domain

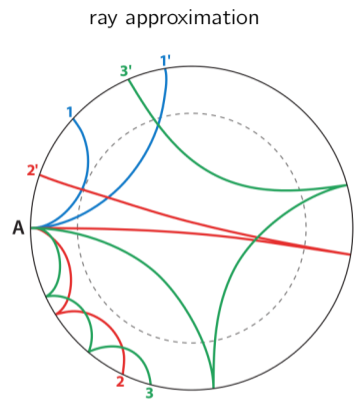
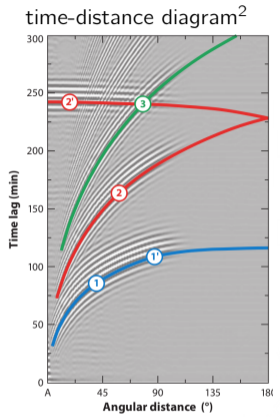
- $\psi(\mathbf{r}_1, t) \rightarrow \hat{\psi}(\mathbf{r}_i, \omega)$
- Observation time (21 years, cadence of 1 min)
 \rightsquigarrow large number of available frequencies
- Cross-correlations

$$C(\mathbf{r}_1, \mathbf{r}_2, \omega) = \hat{\psi}(\mathbf{r}_1, \omega)^* \hat{\psi}(\mathbf{r}_2, \omega)$$

- \mathbf{r}_1 and \mathbf{r}_2 are any points of $4096 \times 4096 \Rightarrow \approx 10^{13}$ cross-correlations per frequency
- Correlation data is extremely noisy \Rightarrow averaging in spatial and frequency domain



Cross-covariance in time-distance diagram:



Time-distance helioseismology³:

Reduce high-dimensional correlation data to smaller number of travel-times.

²L. Gizon, A. C. Birch, H. C. Spruit. Local helioseismology: Three-dimensional imaging of the solar interior. ARAA, 2010.
³T. Duvall Jr., S. Jefferies, J. Harvey, M. Pomerantz. Time-distance helioseismology. Nature, 1993.

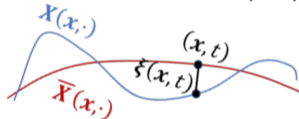


The forward solver: Interior PDE model and discretization

Equations of solar oscillations

Perturbed flow equations

- Assume there is a smooth stationary equilibrium $(\bar{\cdot})$ to the equations of **conservation of momentum and mass** and gravitational potential (no magnetic field yet)
- Trajectory of a particle at \mathbf{x} after **perturbation**: $X(\mathbf{x}, t) = \bar{X}(\mathbf{x}, t) + \xi(\mathbf{x}, t)$



- Consider **Lagrangian perturbation** of conservation of momentum and mass $R(\mathbf{x} + \xi(\mathbf{x}, t), t) - \bar{R}(\mathbf{x}, t)$
- Eulerian perturbation of equations for gravitational potential $R(\mathbf{x}, t) - \bar{R}(\mathbf{x}, t)$
- and **time-harmonic** ansatz $\xi(\mathbf{x}, t) = \text{Re}(\xi \exp(-i\omega t))$

Equations of solar oscillations

We arrive at the following “monster”: (similar to Galbrun’s equation⁵ in Aeroacoustics)



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$$\underbrace{\rho(-i\omega + \mathbf{u} \cdot \nabla + \Omega \times)}_{=:D} \xi - \nabla(\rho c_s^2 \nabla \cdot \xi) + (\nabla \cdot \xi) \nabla p - \nabla(\nabla p \cdot \xi) + (\text{Hess}(p)\xi - \rho \text{Hess}(\phi))\xi - i\gamma\rho\omega\xi + \rho\nabla\varphi = \mathbf{s} \quad \text{in } D,$$

$$-\frac{1}{4\pi G} \Delta\varphi + \nabla \cdot (\rho\xi) = 0 \quad \text{in } \mathbb{R}^3.$$

ξ : Lagrangian displacement: difference between perturbed/unperturbed position,

φ : perturbation of gravitational potential,

c_s : sound speed,

\mathbf{u} : background velocity,

ϕ : gravitational background potential,

ω : frequency,

ρ : density,

Ω : angular velocity,

γ : damping,

p : pressure

+ boundary conditions

⁵H. Galbrun. Propagation d’une onde sonore dans l’atmosphère et théorie des zones de silence. 1931

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Discretization?

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Helmholtz-type decomposition

- straight-forward (DG) discretizations **fail**⁶



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⁶ J. Chabassier, M. Duruflé. Solving time-harmonic Galbrun's equation with an arbitrary flow. Application to Helioseismology. 2018.

⁷ M. Halla, T. Hohage. On the well-posedness of [...] and the equations of stellar oscillations. SIMA, 2021

Helmholtz-type decomposition



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- straight-forward (DG) discretizations **fail**⁶
- Let's consider the **leading order terms** (for ξ):

$$+\rho(-i\omega + \mathbf{u} \cdot \nabla + \Omega \times)^2 \xi - \nabla(\rho c_s^2 \nabla \cdot \xi) - i\rho\gamma\omega\xi + \dots = f$$

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- crucial in the analysis⁷ is a Helmholtz-type decomposition of solution space

$$\mathbb{V} = \{\xi \in \mathbf{L}^2(D) : \nabla \cdot \xi \in L^2(D), (\mathbf{u} \cdot \nabla)\xi \in \mathbf{L}^2(D), \nu \cdot \xi = 0 \text{ on } \partial D\} = \mathbb{X} \oplus \mathbb{Y} \oplus \mathbb{Z}$$

with

- \mathbb{X} : (generalized) divergence-free functions
- \mathbb{Y} : gradients (compactly emb. in \mathbf{L}^2) with $\|\nabla \cdot \mathbf{y}\|_0 + \|\mathbf{y}\|_0 \gtrsim \|\mathbf{y}\|_{\mathbb{V}}$ for all $\mathbf{y} \in \mathbb{Y}$
- \mathbb{Z} : a finite dimensional subspace

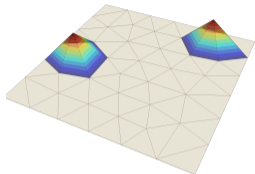
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Discretizations with Helmholtz-type decomposition



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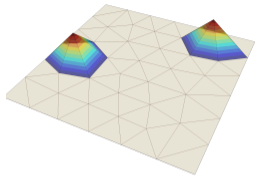
Finite Element Methods

- based in calculus of variation
→ solve variational formulation over finite dimensional space
- approximate solution using polynomials on each mesh element

Discretizations with Helmholtz-type decomposition



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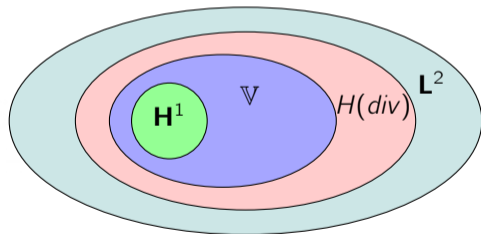


Finite Element Methods

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Choice of discretization (space)?

- natural choice: $\mathbb{V}_h \subset H(\text{div})$
- $\mathbb{V}_h \subset H(\text{div}) \rightsquigarrow$ Helmholtz-type decomposition
- but: many more choices are possible...



A simple model problem

[Ma. project of T. Alemán]⁸



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Simplified version (real, with artificial reaction term): Find $\xi \in \mathbb{V}$, s.t.

$$\langle c_s^2 \rho \nabla \cdot \xi, \nabla \cdot \eta \rangle - \underbrace{\langle \rho (\mathbf{u} \cdot \nabla) \xi, (\mathbf{u} \cdot \nabla) \eta \rangle + \|\mathbf{u}\|_\infty \langle \rho \xi, \eta \rangle}_{a(\xi, \eta)} = \langle f, \eta \rangle \quad \forall \eta \in \mathbb{V}.$$

Generic discretization ($\mathbb{V} \rightsquigarrow \mathbb{V}_h$, $\nabla \cdot \rightsquigarrow \nabla_h \cdot$, $a(\cdot, \cdot) \rightsquigarrow a_h(\cdot, \cdot)$): Find $\xi_h \in \underline{\mathbb{V}}_h$, s.t.

$$\langle c_s^2 \rho \underline{\nabla}_h \cdot \xi_h, \underline{\nabla}_h \cdot \eta_h \rangle - \underline{a}_h(\xi_h, \eta_h) = \langle f, \eta_h \rangle \quad \forall \eta_h \in \underline{\mathbb{V}}_h.$$

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Discrete Helmholtz decomposition

$$\mathbb{X}_h = \{\xi_h \in \underline{\mathbb{V}}_h : \nabla_h \cdot \xi_h = 0\} \quad \mathbb{Y}_h = \mathbb{X}_h^\perp = \{\xi_h \in \underline{\mathbb{V}}_h : \underline{a}_h(\xi_h, \eta_h) = 0 \quad \forall \eta_h \in \mathbb{X}_h\}$$

$$\text{and } c \|\mathbf{y}_h\|_{\underline{\mathbb{V}}_h} \leq \|\nabla_h \cdot \mathbf{y}_h\|_0 \quad \forall \mathbf{y}_h \in \mathbb{Y}_h, \quad c \neq c(h, c_s).$$

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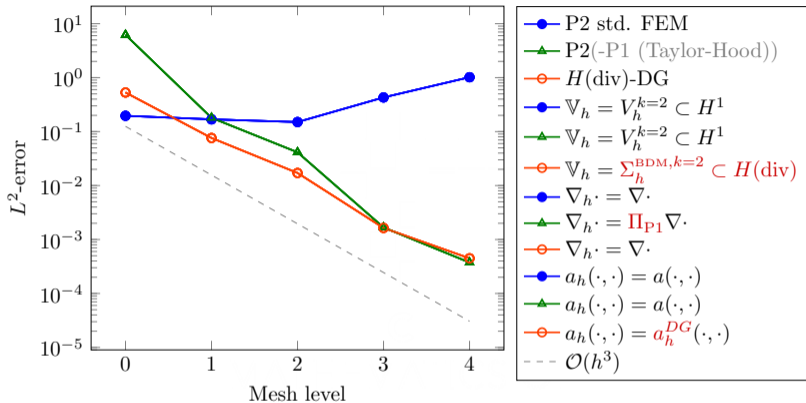
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Good news: This is achieved by every inf-sup stable Stokes element!

 \rightsquigarrow Choose \mathbb{V}_h , $\nabla_h \cdot$, $a_h(\cdot, \cdot)$ suitable for a Stokes(-type) problem.

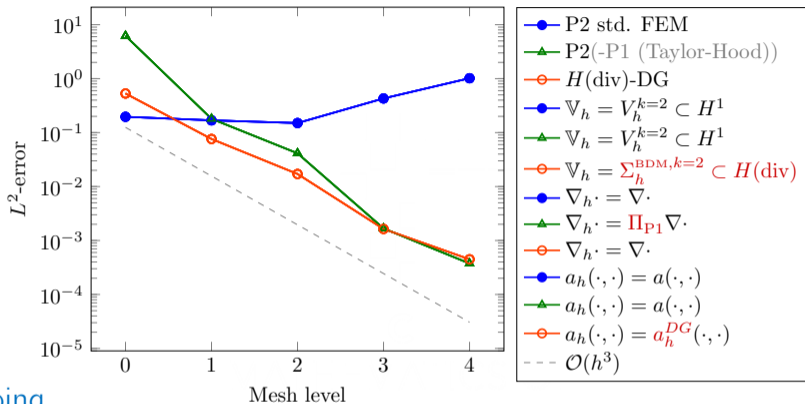
Numerical example for simplified problem



Numerical example for simplified problem



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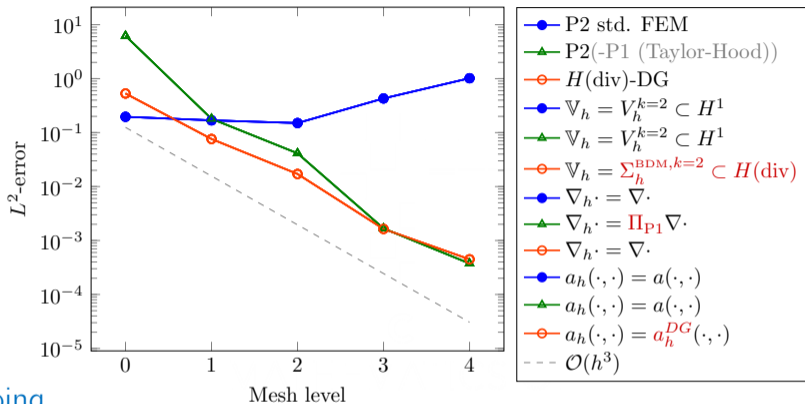


Ongoing

- Convergence analysis for full problem
- Numerics for full problem



Numerical example for simplified problem



Ongoing

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boundary conditions?



The forward solver: Boundary conditions for the Sun

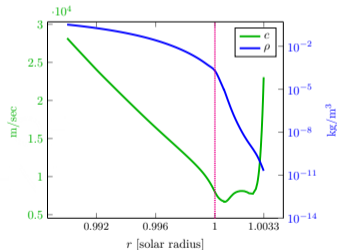
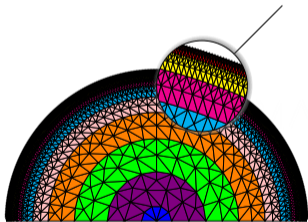
Boundary conditions for helioseismology

Simplified scalar model:

$u = c_s \nabla \cdot \xi$, current working horse (no gravity effects):

$$\left(\sqrt{\rho} \Delta (\rho^{-\frac{1}{2}}) - \frac{(\omega + i\gamma)^2}{c_s^2} \right) u - \Delta u = f$$

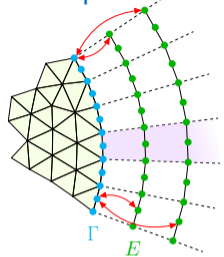
Atmosphere: No **flows**, spherically symmetric sound speed $c_s(r)$ and density $\rho(r)$ (separability).



Transparent bound. cond. are needed to truncate simulations close to surface!
Std. approaches (PML, loc. b.c.) fail due to **rapidly changing material params..**



Tensor-product type boundary conditions

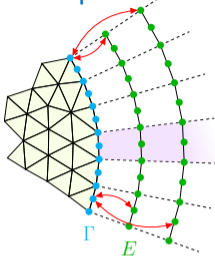


- Many popular transparent b.c. follow (inherently **sparse**) ansatz for discretization of exterior diff. op:

$$\begin{bmatrix} A_{\Gamma\Gamma} & A_{\Gamma E} \\ A_{E\Gamma} & A_{EE} \end{bmatrix} \otimes \underbrace{M}_{\approx \text{Id}_\Gamma} + \begin{bmatrix} B_{\Gamma\Gamma} & B_{\Gamma E} \\ B_{E\Gamma} & B_{EE} \end{bmatrix} \otimes \underbrace{K}_{\approx -\Delta_\Gamma}$$

- Here, $A, B \in \mathbb{C}^{(N+1) \times (N+1)}$ small matrices which encode the discrete transparent b.c.. **How to choose them?**

Tensor-product type boundary conditions



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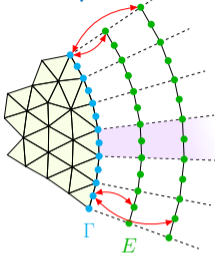
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Observation (assuming discretization in radial direction only)

- The \mathcal{DtN} map (representing the exterior solution operator) can be characterized by (computable) numbers $\mathcal{dtn}(\lambda)$ ($\lambda \in \Delta_{\Gamma}$)
- The discrete exterior solution operator can be characterized by numbers $\mathcal{dtn}_N(\lambda) = f(\lambda, A, B)$ ($\lambda \in \Delta_{\Gamma}$)

Tensor-product type boundary conditions



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Idea of **learned infinite elements**⁹:

Optimize A and B to match known (computable) \mathcal{dtn} !

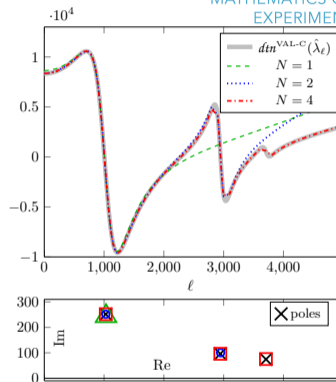
Learned infinite elements ⁹

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- Solve rational approximation problem ($\omega_\ell \geq 0$)

$$\min_{A, B \in \mathbb{C}^{(N+1) \times (N+1)}} \sum_{\ell} \omega_{\ell}^2 |dtn(\lambda_{\ell}) - dtn_N(\lambda_{\ell})|^2.$$

- Minimizers A and B represent local element matrices of **learned infinite elements**.
- Error analysis guarantees¹⁰ **exponential** convergence on finite intervals using only $\mathcal{O}(N)$ DOFs.



Approx. results for realistic
chromospheric model

⁹T. Hohage, C.L., J. Preuß, Learned infinite elements, SISC 2021.

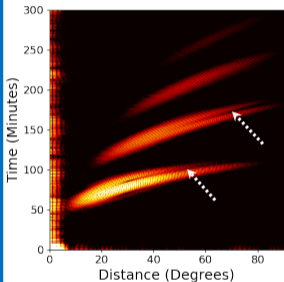
¹⁰J. Preuß, Learned infinite elements for helioseismology, PhD thesis. 2021.

Comparison

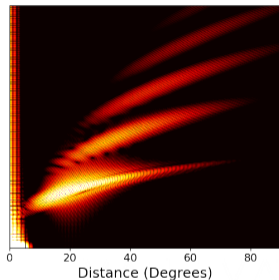
Time distance diagrams with diff. exterior domain models



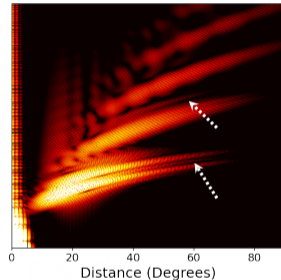
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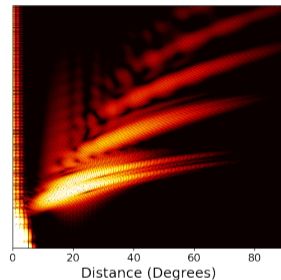
(a) MDI observations



(b) Atmo
(allows for abs. b.c.)



(c) VAL-C
(meshed)



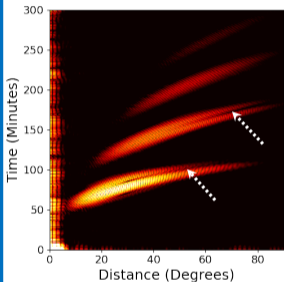
(d) Learned IE
(lowest order)

Comparison

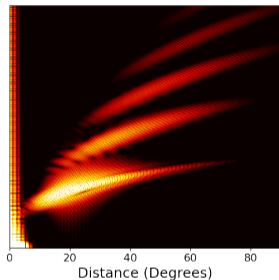
Time distance diagrams with diff. exterior domain models



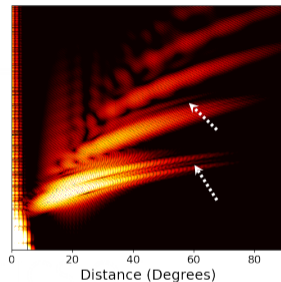
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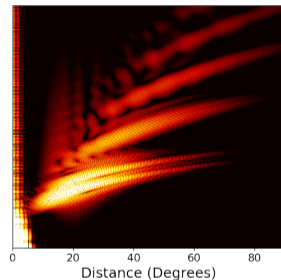
(a) MDI observations



(b) Atmo
(allows for abs. b.c.)



(c) VAL-C
(meshed)



(d) Learned IE
(lowest order)

Learned infinite elements are flexible w.r.t. to atmospheric model!



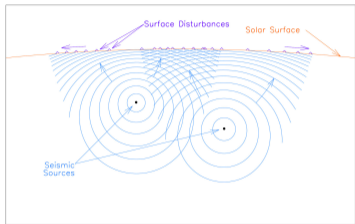
The inverse problem: Iterative holography (advertisement)

Helioseismic Holography



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- Forward problem: $\mathcal{L}\psi = r + s$,
 r, s : (stochastic) sources (bnd./int.), ψ wave field

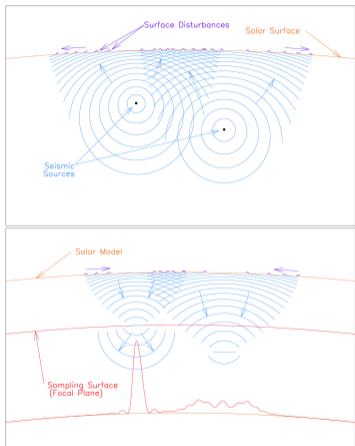


Seismic waves propagating
to/from solar surface¹¹.

Helioseismic Holography



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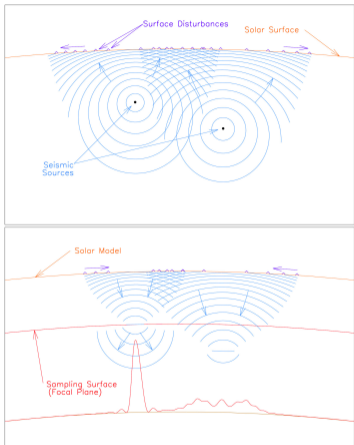
Seismic waves propagating to/from solar surface¹¹.

- Forward problem: $\mathcal{L}\psi = r + s$,
 r, s : (stochastic) sources (bnd./int.), ψ wave field
- Solve similar problem (backwards): $\mathcal{L}\phi = \psi$,
where ψ takes the role of r (available data).

Helioseismic Holography



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- Alternative. Hologram:

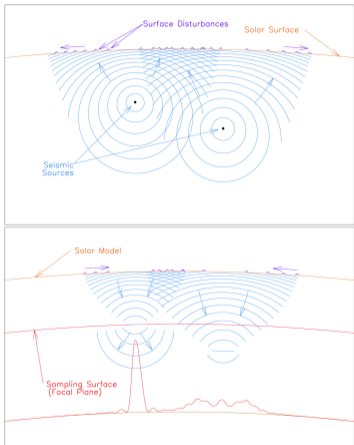
$$\Phi_{\alpha}^{\omega}(x) = \int_A H_{\alpha}^{\omega}(x, r') \psi(r', \omega) dr',$$

H_{α}^{ω} : wave (back)propagator, A : observed part of surface

Helioseismic Holography



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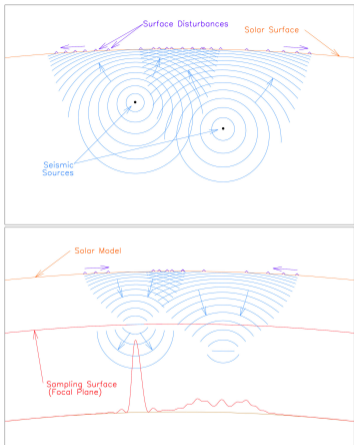
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- Holography has been successfully used (farside imaging)

Helioseismic Holography



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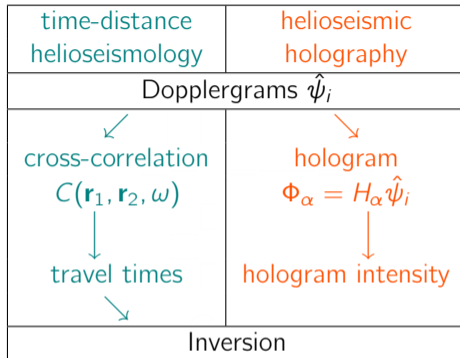
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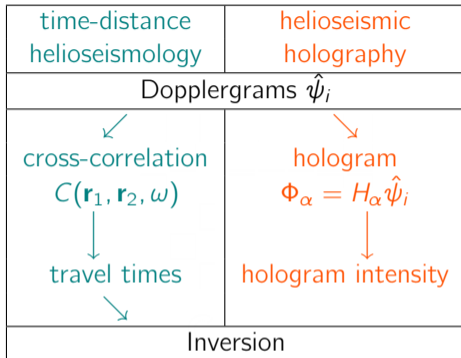
- Holography has been successfully used (farside imaging)
- But: Holography is not a quantitative method

Helioseismic inverse problems



Helioseismic inverse problems

huge set of data →
reduction →
(loses information)

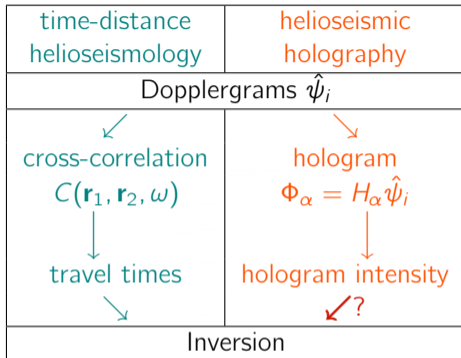


← qualitative only



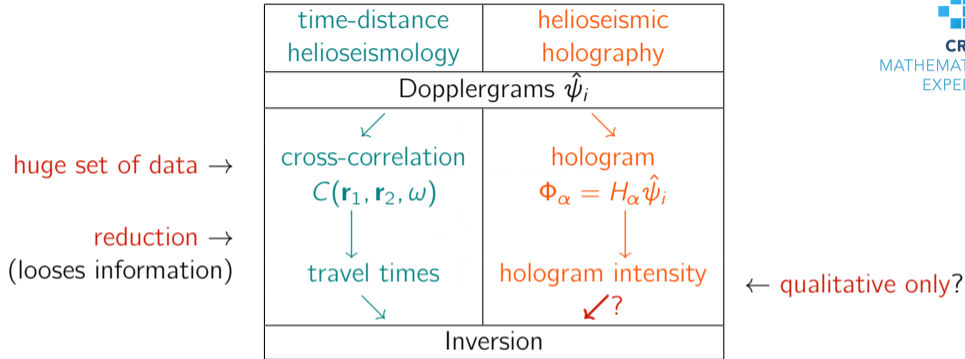
Helioseismic inverse problems

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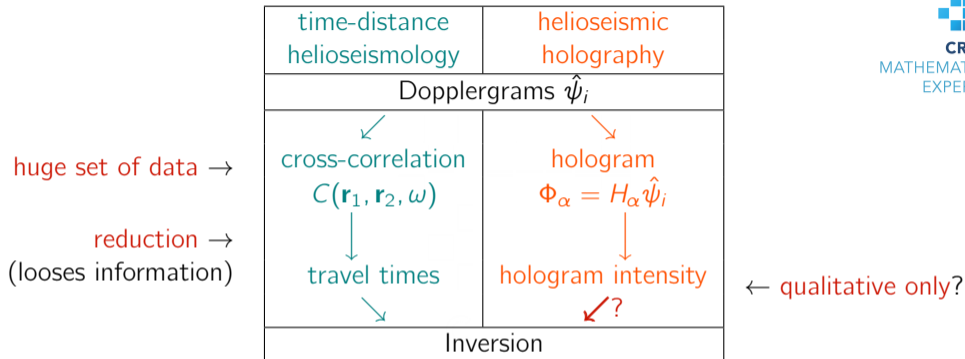
← qualitative only?

Helioseismic inverse problems



Can we turn holography into a quantitative method?

Helioseismic inverse problems



Can we turn holography into a quantitative method?

Yes! **holographic backpropagation** can be understood as **adjoint of covariance operator**

↪ allows to applied standard iterative inverse solvers

⇒ quantitative helioseismic holography (by iteration)

⇒ Helioseismic inversion without setup of full correlation data.

↪ details: poster session C04

Conclusion



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Data

- Large data sets (> 20 years, cadence ≈ 1 min, 4096^2 pixel)
- Correlation data is even larger (\rightsquigarrow travel times)

Forward solver

- Scalar equation is working horse (does not capture gravity)
- Learned infinite elements allow us to deal with complex atmosphere
- Vector PDE is challenging (robust discretizations & efficiency)

Inversion

- so far: time distance helioseismology and helioseismic holography
- holography made quantitative (by iteration)

Conclusion

Data

- Large data sets (> 20 years, cadence ≈ 1 min, 40962 samples)
- Correlation data is even larger (\approx travel times)

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- Scalar equations: working horse (does not capture complexity)
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Inversion

- so far: time distance helioseismology and helioseismic holography
- holography made quantitative (by iteration)

Thank you for your attention!

More details? \rightsquigarrow