

# Unfitted mixed finite element methods

Guosheng Fu<sup>1</sup>, Christoph Lehrenfeld<sup>2</sup>, Tim van Beeck<sup>2</sup>



ECCOMAS, Oslo, June 6, 2022

$$\begin{pmatrix} A_{\text{?}} & B^T_{\text{?}} \\ B_{\text{?}} & -_{\text{?}} \end{pmatrix} \cdot \begin{pmatrix} u \\ p \end{pmatrix} = \begin{pmatrix} g \\ h \end{pmatrix}$$

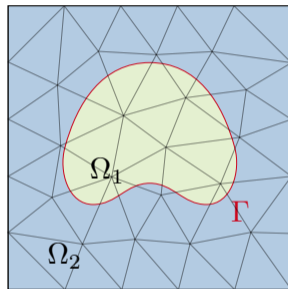
# Background: Unfitted FEM

## Problems

- PDEs on domains with separate geometry description (e.g. level set)
- PDEs on embedded surfaces
- PDEs on moving domains

## Challenges

- FE formulation in unfitted setting
- **Stability/robustness for arbitrary (small) cuts**
- Imposition of boundary/interface conditions
- Cut integration (robust / high order accurate)



## Solution techniques

- unfitted FE spaces (CutFEM / XFEM / Finite Cell / Unfitted FEM / ...)
- Weak imposition of boundary conditions through Nitsche / stab. Lagrange mult.
- **Ghost (👻) penalty** / aggregated FEM

# Background: Unfitted FEM

## Problems

- PDEs on domains with separate geometry description (e.g. level set)
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■ we want to do unfitted FEM

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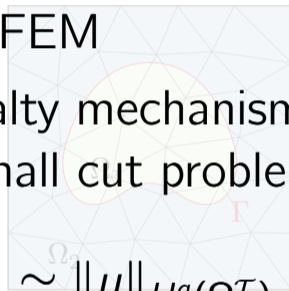
■ we know the ghost penalty mechanism as one tool to deal with small cut problems:

$$\|u\|_{H^q(\Omega)} + \|u\|_{\text{ghost},q} \simeq \|u\|_{H^q(\Omega^T)}$$

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## Examples: Mixed formulation of the Poisson and Stokes problems

Mixed Poisson/Darcy:

Find  $u, p$  with  $p = p_D$  on  $\partial\Omega$ , s.t.

$$\begin{aligned} K^{-1}u - \nabla p &= 0 & \text{in } \Omega, \\ \operatorname{div} u &= -f & \text{in } \Omega. \end{aligned}$$

Stokes:

Find  $u, p$  with  $u = u_D$  on  $\partial\Omega$ , s.t.

$$\begin{aligned} -\Delta u + \nabla p &= f & \text{in } \Omega, \\ \operatorname{div} u &= 0 & \text{in } \Omega, \end{aligned}$$

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General unfitted saddle point problems

$$\begin{aligned} \text{Find } (u, p) \in \Sigma \times Q, \text{ s.t. } \quad a(u, v) + b(v, p) &= g(v), \quad \forall v \in \Sigma, \\ b(u, q) &= h(q), \quad \forall q \in Q. \end{aligned}$$

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⚡ (inf-sup) stability in the presence of arbitrary cuts ?

- Stokes (advantage: H1-conformity) based on stable fitted method:
  - Stabilized vel./press. pairs<sup>1</sup>
  - Taylor-Hood<sup>2,3</sup>
  - Scott-Vogelius (macro-element version, exactly divfree<sup>\*</sup>) [+grad-div]<sup>4</sup>
- Poisson/Darcy and Stokes-Darcy based on stable fitted method:
  - $RT^k / BDM^k \times P^k$  (inf-sup-stable (in the fitted case) pairs)<sup>5,6</sup>

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Stabilized formulations:

$$\text{Find } (u_h, p_h) \in \Sigma \times Q, \text{ s.t. } \begin{aligned} (a_{(h)} + \text{🧛}_u)(u_h, v_h) + b_{(h)}(v_h, p_h) &= g(v_h), \quad \forall v_h \in \Sigma_h, \\ b_{(h)}(u_h, q_h) - (d_h + \text{🧛}_p)(p_h, q_h) &= h(q_h), \quad \forall q_h \in Q_h. \end{aligned}$$

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↔ inf-sup-stability of global bilinear form (independent of cut position) 🧟, but mass conservation polluted ⚡

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For Darcy interface problem:

- $\mathbb{RT}^0 \times \mathbb{P}^0$  (inf-sup-stable pair\*) (low order, 2D) <sup>7</sup>
- $\mathbb{RT}/\mathbb{BDM} \times \mathbb{P}^k$ , inf-sup-stable pair\* + 🧛-penalties for divergence <sup>8</sup>

$$\begin{aligned} \text{Find } (u_h, p_h) \in \Sigma_h \times Q_h, \text{ s.t. } & (a + \text{🧛}_u)(u_h, v_h) + (b + \text{🧛}^*)(v_h, p_h) = g(v_h), \quad \forall v_h \in \Sigma_h, \\ & (b + \text{🧛}^*)(u_h, q_h) = h(q_h), \quad \forall q_h \in Q_h. \end{aligned}$$

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- mass balance hardly polluted  
(effectively using a smooth ext of  $f$  on the active mesh, possibly by patch-🧛-penalties)
- $f \in \mathbb{P}^k \Rightarrow \text{div } u_h = -f$

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**Aim now:** Robustness w.r.t. cut position (also high order) w/o pollution of mass balance

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## A step back: Fitted mixed Poisson (recap)

Find  $u_h \in \Sigma_h = \mathbb{RT}^k \subset H(\operatorname{div}, \Omega)$ ,  $p_h \in Q_h = \operatorname{div} \Sigma_h = \mathbb{P}^k \subset L^2(\Omega)$ , s.t.

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- $\Sigma_h = \Sigma_h^0 \oplus_a \Sigma_h^\perp$  with  $\Sigma_h^0 = \ker b = \{u_h \in \Sigma_h \mid \operatorname{div} u_h = 0\}$  and  $a(\cdot, \cdot) = (\cdot, \cdot)_\Omega$ .
- 3 subproblems for 3 unknowns:  $(u_h, p_h) \rightsquigarrow (u_h^0, u_h^\perp, p_h)$ 
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- Discrete LBB-stability:  $\inf_{q_h} \sup_{u_h} \frac{b(u_h, q_h)}{\|u_h\|_\Sigma \|q_h\|_Q} \geq c > 0 \quad \Rightarrow$  stability of (2) & (3)

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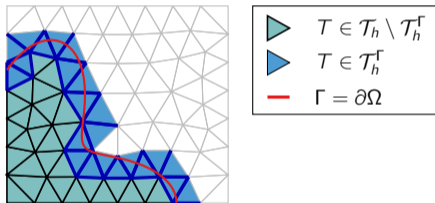
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- With  $\operatorname{div} \Sigma_h \subset Q_h$  (2) also reads as  $\operatorname{div} u_h + \Pi_{Q_h} f = 0$  (*pointwise*)

# Unfitted Mixed FEM

Starting point: straight-forward unfitted Mixed FEM:

Find  $u_h \in \Sigma_h = \mathbb{RT}^k(\mathcal{T}_h) \subset H(\operatorname{div}, \Omega^T)$ ,  $p_h \in Q_h = \mathbb{P}^k(\mathcal{T}_h) \subset L^2(\Omega^T)$ , s.t.

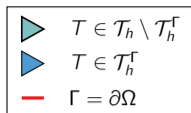
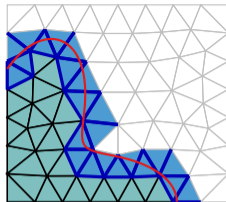
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- (1) Determine  $u_h^0$  from  $a_h(u_h^0, v_h^0) = (u_h^0, v_h^0)_\Omega = g(v_h^0) \quad \forall v_h^0 \in \Sigma_h^0$
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# Adjusted unfitted mixed FEM

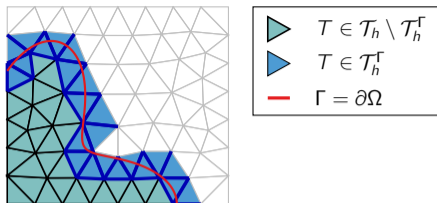


Observation on the subspace  $\Sigma_h^0$

Due to  $\operatorname{div} \Sigma_h \subset Q_h$  we have  $\ker b =$  pointwise divergence-free functions

$$\Rightarrow \Sigma_h^0 = \{u_h \in \Sigma_h \mid b(u_h, q_h) = 0 \forall q_h \in Q_h\} = \ker b = \ker b_h \text{ with } b_h(u_h, q_h) := (\operatorname{div} u_h, q_h)_{\Omega^T}$$

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Adjusted unfitted Mixed FEM:

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■  $\gamma_{\text{jump}} > 0$  ( $\gamma_{\text{jump}} = 0$  possible)

■ Assume  $f_h \in Q_h$  with  $f_h \approx \mathcal{E}f$  in  $\Omega^T$  (with  $\mathcal{E}$  smooth ext. op. from  $\Omega$  to  $\Omega^{\varepsilon} \supset \Omega^T$ .)

## The subproblems for $u_h$ :

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Symmetric saddle point problem; well-conditioned linear systems.

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Subproblems (1) & (2) for  $u_h^0 \in \Sigma_h^0$  and  $u_h^\perp \in \Sigma_h^\perp$ :

- $a_h(u_h^0, v_h^0) = (u_h^0, v_h^0)_\Omega + \gamma_{\text{adj}}(u_h^0, v_h^0) = g(v_h^0) = (v_h^0, p_D)_{\partial\Omega} \quad \forall v_h^0 \in \Sigma_h^0$   
Consistent, continuous, coercive (w.r.t.  $\|\cdot\|_{H(\operatorname{div}; \Omega^T)}$ ).

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<sup>8</sup>T. Frachon, P. Hansbo, E. Nilsson, S. Zahedi, *A divergence preserving cut finite element method for Darcy flow*. arXiv: 2205.12023

## The subproblems for $u_h$ :

### Adjusted unfitted Mixed FEM:

Find  $u_h \in \Sigma_h = \mathbb{RT}^k(\mathcal{T}_h)$ ,  $\bar{p}_h \in Q_h = \mathbb{P}^k(\mathcal{T}_h)$ , s.t.

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### Error estimate for $u_h$

$[u_h]$  is the same as in [8] if  $f_h$  is a  $\gamma_{\text{pen}}$ -penalty-based discrete ext. of  $f$

$$\|u - u_h\|_{H(\operatorname{div}; \Omega^T)} \lesssim \|u - \Pi^{\Sigma_h} u\|_{L^2(\Omega^T)} + \|\Pi^{Q_h} \mathcal{E}f - f_h\|_{L^2(\Omega^T)} \lesssim h^{k+1},$$

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## Lagrange Multiplier $\bar{p}_h$

Subproblem (3) for  $\bar{p}_h \in Q_h$ :

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# Lagrange Multiplier $\bar{p}_h \rightsquigarrow p_h^*$

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- $\rightsquigarrow$  Replace (3) with a different way to obtain  $p_h$
- Accurate  $u_h \in \mathbb{RT}^k \rightsquigarrow$  recover  $p_h^* \in Q_h^+ = \mathbb{P}^{k+1}(\mathcal{T}_h)$

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## Element-local post-processing:

On each element  $T \in \mathcal{T}_h$ :

$$(\nabla p_h^*, \nabla q_h^*)_T = (u_h, \nabla q_h^*)_T \quad \forall q_h^* \in \mathcal{P}^{k+1}(T) \setminus \mathbb{R},$$

$$(p_h^*, 1)_T = (\bar{p}_h, 1)_T \text{ if } T \in \mathcal{T}_h \setminus \mathcal{T}_h^\Gamma,$$

$$(p_h^*, 1)_{T \cap \partial\Omega} = (p_D, 1)_{T \cap \partial\Omega} \text{ if } T \in \mathcal{T}_h^\Gamma.$$

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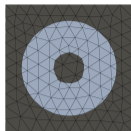
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Alternative: Patch-local post-processing (preserve mean value on uncut elements)

# Numerical example: mixed Poisson on a ring, manufactured solution

- $\text{RT}^k \times \mathbb{P}^k$
- isoparametric unfitted FEM



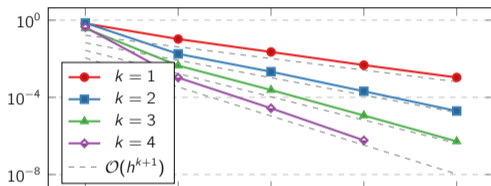
- postprocessing involving  $p_D$
- uniform refinements

$$\|u_h - u\|_{L^2(\Omega)}$$

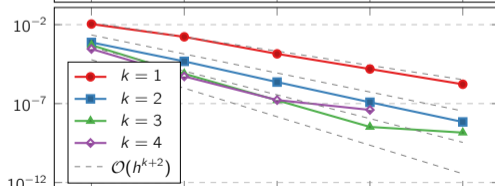
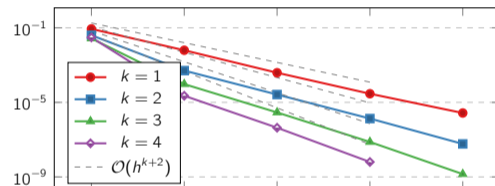
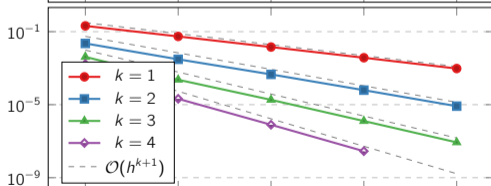
$$\|p_h^* - p\|_{L^2(\Omega)}$$



$(\gamma_{\text{iso}} = 1)$



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Neumann boundary conditions:  $\bar{p} \equiv \bar{p}_D \rightsquigarrow u \cdot n = u_{D,n}$  on  $\partial\Omega$

## Stabilized Lagrange Multiplier Approach

(similar to [9])

Find  $u_h \in \Sigma_h = \mathbb{RT}^k(\mathcal{T}_h)$ ,  $\bar{p}_h \in Q_h = \mathbb{P}^k(\mathcal{T}_h)$ ,  $\lambda_h \in \Lambda_h = \mathbb{P}^k(\mathcal{T}_h^\Gamma)$ , s.t.

$$\begin{aligned} (u_h, v_h)_\Omega + \gamma_{\text{stabilizer}}(u_h, v_h) + (\operatorname{div} v_h, \bar{p}_h)_{\Omega^\Gamma} - (v_h \cdot n, \lambda_h)_{\partial\Omega} &= g(v_h) = 0 \quad \forall v_h \in \Sigma_h, \\ (\operatorname{div} u_h, q_h)_{\Omega^\Gamma} &= (-f_h, q_h)_{\Omega^\Gamma} \quad \forall q_h \in Q_h, \\ (u_h \cdot n, \mu_h)_{\partial\Omega} - \lambda(\lambda_h, \mu_h) &= (u_{D,n}, \mu_h)_{\partial\Omega} \quad \forall \mu_h \in \Lambda_h. \end{aligned}$$

- $\lambda(\cdot, \cdot)$ :
  - smoothing type penalties
  - + volume gradient stabilization weakly enforcing  $\nabla \lambda_h \cdot n \approx 0$
- $\lambda_h - \mu_h$ -block  $\lambda(\lambda_h, \mu_h)$  not invertible
- symmetric saddle-point problem
- Mass balance stays "clean" (in the volume).
- Patch-wise postprocessing unaffected.

<sup>8</sup>T. Frachon, P. Hansbo, E. Nilsson, S. Zahedi, *A divergence preserving cut finite element method for Darcy flow*. arXiv: 2205.12023

<sup>9</sup>E. Burman, *Projection Stabilization of Lagrange Multipliers for the Imposition of Constraints on Interfaces and Boundaries*. NMPDE, 2013

# Conclusion & Outlook

## Unfitted mixed FEM

- Circumvent polluting the mass balance (one of the main features of mixed formulations)
- Exploit **pointwise** character of constraint
  - to go from **div**-constraint on  $\Omega$  to  $\Omega^T$
  - (or to apply  $\mathbb{D}^*(u_h, q_h)$  as in [8])
- Split into 3 subproblems (**inconsistency only affects  $p_h$** )
- Use **post-processing** techniques to recover  $p_h^*$  (higher order)

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## Extensions

- Analysis Neumann case
- $\gamma_{\mathbb{R}} = 0$  possible? (**-**: condition, postprocess.; **+**: hybridization) / hybridiz. on patches
- $\rightsquigarrow$  Stokes / Navier-Stokes:
  - velocity space  $H(\mathbf{div})$ -conforming ( $H^1$ -non-conforming)  $\rightsquigarrow$  exactly div-free
  - $a_h(\cdot, \cdot)$  includes DG terms and  $\mathbb{R}_u$ -penalties
  - $f = f_h = 0$
  - Dirichlet bnd. correspond to Neumann case (last slide)

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Thank you for your attention!

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