

The Trefftz approach for unfitted finite element methods

Christoph Lehrenfeld



joint work with Fabian Heimann¹, Erik Schlesinger², Paul Stocker³, Henry v. Wahl⁴
¹UCL London, ²University of Göttingen, ³University of Vienna, ⁴University of Jena

May 14, 2024

Contemporary Challenges in Trefftz Methods, from Theory to Applications



Banff International Research Station
for Mathematical Innovation and Discovery

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GEORG-AUGUST-UNIVERSITÄT
GÖTTINGEN IN PUBLICA COMMODA

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Disclaimer:

Motivation is not primarily wave equations

Instead:

Extending the Trefftz concept
to a larger class of applications

Contemporary Challenges in Trefftz Methods, from Theory to Applications



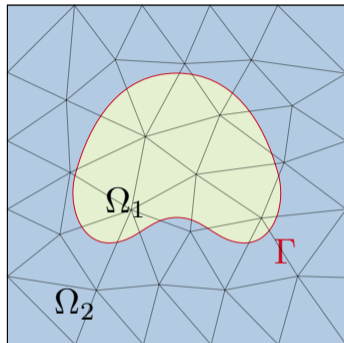
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Motivation: Unfitted FEM

💡 Idea of unfitted discretizations:

It can be beneficial to separate geometry and mesh for

- time-dependent geometries (avoiding remeshing)
- avoiding (non-trivial) meshing



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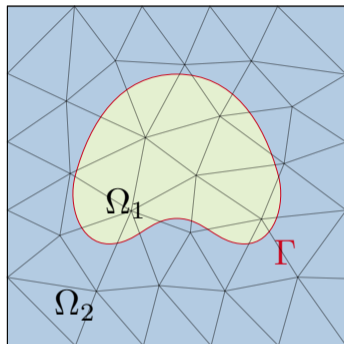
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Challenges in unfitted finite elements:

- arbitrary small cuts cause stability issues.
- implementation of unfitted boundary conditions
- geometry description
- cut integration
- time integration
- linear solvers, ...



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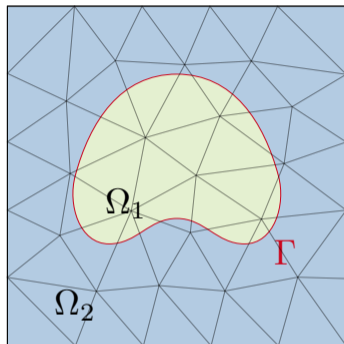
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Problem classes:

1 **one-domain problems**
(fictitious domain)

■ interface problems

2 **surface PDEs**

Example problem: Poisson equation on an unfitted mesh

Consider

$$\begin{aligned} -\Delta u &= f && \text{in } \Omega, \\ u &= g && \text{on } \Gamma = \partial\Omega. \end{aligned}$$

as prototypical elliptic problem on an unfitted mesh.

Setting:

- Geometry description **independent of the mesh**
- \mathcal{T}_h : active submesh with cut elements.
- FE space based on \mathcal{T}_h

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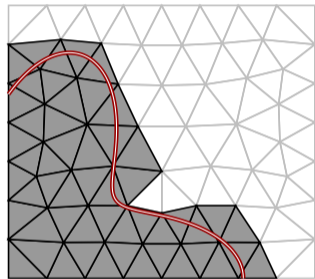
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Setting:

- Geometry description **independent of the mesh**
- \mathcal{T}_h : active submesh with cut elements.
- FE space based on \mathcal{T}_h

Starting point:

- **discontinuous Galerkin discretisation** (Trefftz later)
- weak imposition of boundary conditions through **Nitsche**



Level set geometry on an unfitted mesh with active elements marked

Unfitted DG discretisation (symmetric interior penalty)

Find $u_h \in \mathbb{P}^k(\mathcal{T}_h)$, s.t. $a_h(u_h, v_h) = \ell_h(v_h) \quad \forall v_h \in \mathbb{P}^k(\mathcal{T}_h)$.

$$\begin{aligned}
 a_h(u, v) &= \sum_K \int_{K \cap \Omega} \nabla u \cdot \nabla v \, dx + \int_{K \cap \Gamma} \overbrace{-\mathbf{n} \cdot \nabla u \, v}^{\text{consistency}} \overbrace{-u \mathbf{n} \cdot \nabla v}^{\text{symmetry}} \overbrace{+\lambda k^2 h^{-1} u \, v \, ds}^{\text{stability}} \\
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$\{\{\cdot\}\}$: average across facet, $[\![\cdot]\!]$: jump across facet \rightsquigarrow communication between facets.

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Unfitted DG discretisation (symmetric interior penalty)

Find $u_h \in \mathbb{P}^k(\mathcal{T}_h)$, s.t. $a_h(u_h, v_h) + \text{ghost}_h(u_h, v_h) = \ell_h(v_h) \quad \forall v_h \in \mathbb{P}^k(\mathcal{T}_h)$.

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Add **ghost penalty** () stabilization or repair mesh by cell merging.

Unfitted Stabilisation: 🧸 Penalty

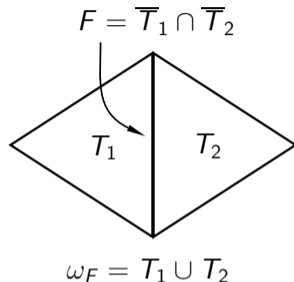
Direct version of the 🧸-penalty operator:

$$\mathbb{G}_h(u, v) = \sum_{F \in \mathcal{F}_h} \frac{\gamma_{\mathbb{G}_h}}{h^2} \int_{\omega_F} [[u]]_{\omega_F} [[v]]_{\omega_F} dx$$

Here $[[u]]_{\omega_F} := u_1 - u_2$ with $u_i = \mathcal{E}u|_{T_i}$,
 $\mathcal{E}: \mathbb{P}^m(K) \rightarrow \mathbb{P}^m(\mathbb{R}^d)$: canonical pol. ext. to \mathbb{R}^d .

This gives us the crucial property

$$\|v\|_{T_1}^2 \lesssim \|v\|_{T_2}^2 + h^2 \mathbb{G}_h^F(v, v).$$



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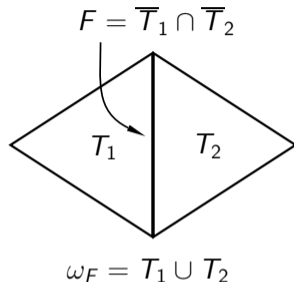
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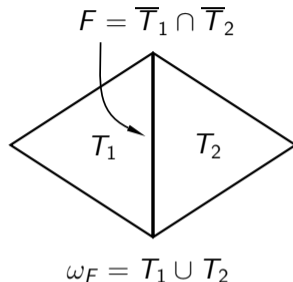
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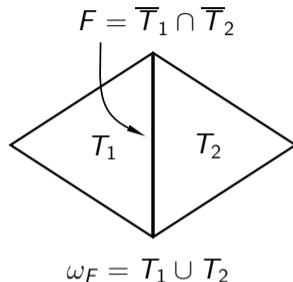
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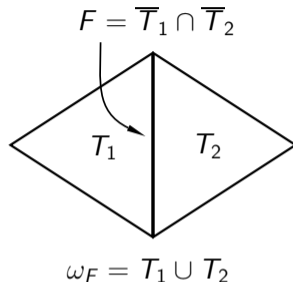
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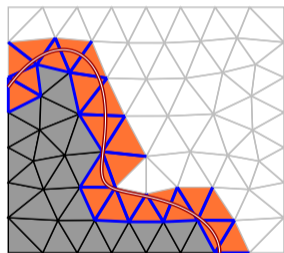
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How to choose $\mathcal{F}_h^{\mathbb{G}}$?

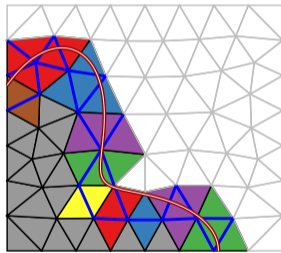







Stabilization facets $\mathcal{F}_h^{\text{stab}}$ for the penalty

Form patches that allow to reach **one good element** from **every (ill-)cut element**.



-  $T \in \mathcal{T}_h \setminus \mathcal{T}_h^\Gamma$
-  $T \in \mathcal{T}_h^\Gamma$
-  $F \in \mathcal{F}_h(\mathcal{T}_h^{\text{act}}) \setminus \mathcal{F}_h^{\text{stab}}$
-  $F \in \mathcal{F}_h^{\text{stab}}$
-  Γ



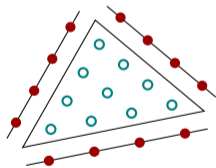
-  $\mathcal{T}_h^\omega, \omega \in \mathcal{T}_h^{\text{C}}$
-  $F \in \mathcal{F}_h(\mathcal{T}_h^\omega)$
-  $F \in \mathcal{F}_h(\mathcal{T}_h^{\text{ag}})$
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-  Γ

Unfitted (embedded) Trefftz DG

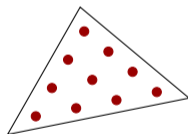
Find $u_h \in \mathbb{T}_f^k(\mathcal{T}_h)$, s.t. $a_h(u_h, v_h) + \text{penalty}_h(u_h, v_h) = \ell_h(v_h) \quad \forall v_h \in \mathbb{T}_0^k(\mathcal{T}_h)$ with

$$\mathbb{T}_f^k(\mathcal{T}_h) := \{v_h \in \mathbb{P}^k(\mathcal{T}_h) : -\Delta v_h = \Pi^{k-2} f \text{ on } K \text{ for all } K \in \mathcal{T}_h\}.$$

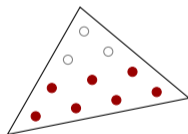
- Complexity reduction similar to Hybrid DG: $\mathcal{O}(h^{-d}k^d) \rightarrow \mathcal{O}(h^{-d}k^{d-1})$
- Coupling pattern (element-to-element) compatible with penalty_h



Hybrid DG



standard DG



Emb. Trefftz DG

- : global dof
- : local dof
- : removed dof

Recovering the DG error estimates

Lemma (H^1 Estimate)

$u \in H^m(\Omega)$ exact solution with $g \in H^{\frac{1}{2}}(\Gamma)$, $f \in L^2(\Omega)$, $u_h \in \mathbb{T}_f^k(\mathcal{T}_h)$ Trefftz solution. Then,

$$\|u - u_h\|_{\mathcal{A}_h} + |u_h|_{\mathcal{G}_h} \lesssim h^l \|u\|_{H^{l+1}(\Omega)}, \quad l = \min\{m - 1, k\}.$$

Theorem (L^2 Estimate)

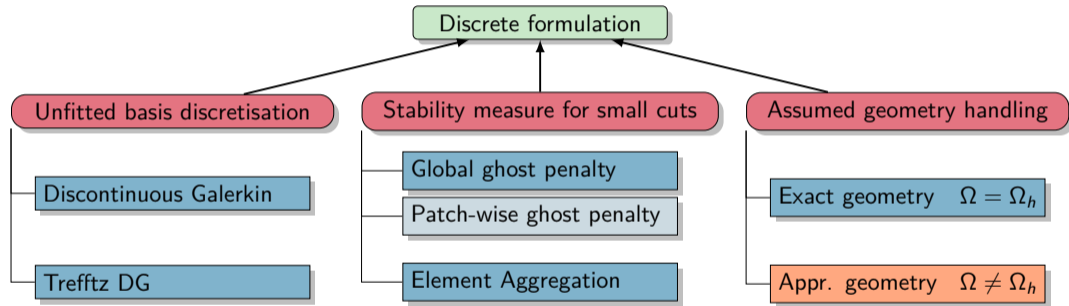
Additionally, assume $L^2(\Omega)$ - $H^1(\Omega)$ -regularity. Then

$$\|u - u_h\|_{\Omega} \lesssim h^{l+1} \|u\|_{H^{l+1}(\Omega)}, \quad l = \min\{m - 1, k\}.$$

Proofs follow 'standard' unfitted + 'standard' Trefftz DG methodology:

- Coercivity for sufficiently large $\gamma_{\mathcal{G}_h}$ and λ
- (patchwise) averaged Taylor polynomial as interpolant of the extended solution (on \mathcal{T}_h)
- Appropriate bound on ghost-penalty contribution.

A few variants



Element aggregation: $\gamma_{\text{ghost}} \rightarrow \infty$ (patch-wise ghost penalty) \rightsquigarrow patchwise harmonic polynomials.

Embedded Trefftz²: Extracting harmonic & aggregated polynomials

Compute patchwise kernel of

$$w_h^\omega(u, v) = \sum_{K \in \omega} h^2(\Delta u, \Delta v)_K + \text{😊}_h^\omega(u, v)$$

$\ker(w_h^\omega)$: harmonic functions that are **one** polynomial on ω .

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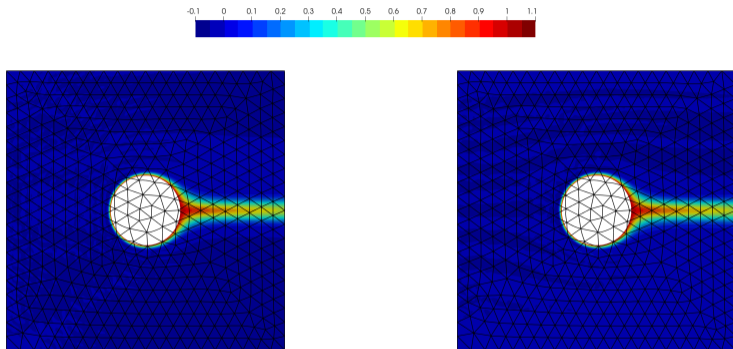
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Setup reduces to:

- Setup linear system for unstabilized (w.r.t. cuts) $\mathbb{P}^k(\mathcal{T}_h)$ discretization
- Setup embedded matrix T corresponding to $\ker(w_h^\omega)$
- Setup reduced system ($T^T A T$ and $T^T b$)
- Solve for aggregated Trefftz DG basis
- Reconstruct solution in $\mathbb{P}^k(\mathcal{T}_h)$

Steps can also be patch-localized (to avoid the global DG assembly).



Right: DG solution; Left: Trefftz DG solution



F. Heimann, C. Lehrenfeld, P. Stocker, H. von Wahl.
Unfitted Trefftz discontinuous Galerkin methods for elliptic boundary value problems.
ESAIM:M2AN 57(5):2803–2833, 2023.

PDEs on surfaces

Example problems:

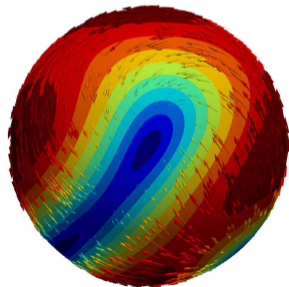
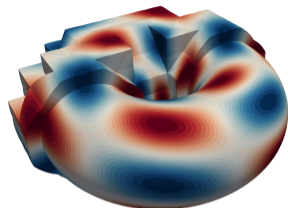
- Laplace-Beltrami equation,

$$u : \Gamma \rightarrow \mathbb{R} \quad - \Delta_{\Gamma} u = f \quad \text{on } \Gamma$$

- Vector Laplace-Beltrami equation,

$$u : \Gamma \rightarrow \mathbb{R}^d \quad - \Delta_{\Gamma} u = f, \quad u \cdot \mathbf{n}_{\Gamma} = 0 \quad \text{on } \Gamma$$

- Surface (Navier-)Stokes equations, ...

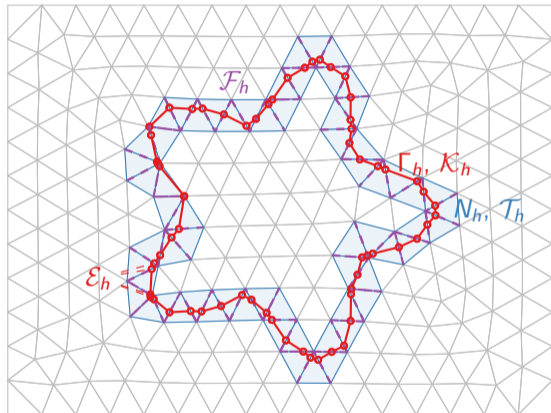


Unfitted FEM DG for Surface PDEs, the Trace FEM DG

Unfitted mesh entities:

- active mesh: \mathcal{T}_h (domain: N_h)
- (background) FE space: $\mathbb{P}^k(\mathcal{T}_h)$
- **irregular!** surface mesh: \mathcal{K}_h (surface: Γ_h)
- edges^a of surface mesh: \mathcal{E}_h
- (active) facets of background mesh: \mathcal{F}_h

^ain the 3D case, vertices otherwise



TraceFEM on irregular cut surface mesh for $-\Delta_\Gamma u = f$ on Γ

Naive discrete bilinear form for (negative) Laplace-Beltrami operator on $\mathbb{P}_{\text{cont}}^k(\mathcal{T}_h)$:

$$a_h(u, v) = \sum_{K \in \mathcal{K}_h} \int_K \nabla_{\Gamma_h} u \cdot \nabla_{\Gamma_h} v, \quad a_h(u, u) = \|\nabla_{\Gamma_h} u\|_{\Gamma_h}^2$$

- $\|\nabla_{\Gamma_h} \cdot\|_{\Gamma_h}$ has a large (near-) kernel: vol. fcts. vanishing on surface

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- $\|\nabla_{\Gamma_h} \cdot\|_{\Gamma_h}$ has a large (near-) kernel: vol. fcts. vanishing on surface

Remedy: **Normal gradient volume stabilisation**

- PDE acts in tangential direction of the surface. Add equation in normal direction:

$$j_h(u, v) = \sum_{T \in \mathcal{T}_h} \int_T \lambda^n (\nabla u \cdot \mathbf{n}_\Gamma)(\nabla v \cdot \mathbf{n}_\Gamma)$$

\mathbf{n}_Γ : quasi-normal vector (extension of surface normal to neighborhood).

Interior penalty Trace DG on irregular cut surface mesh

$$\underbrace{\sum_{K \in \mathcal{K}_h} \int_K \nabla_{\Gamma_h} u \cdot \nabla_{\Gamma_h} v}_{=a_h(u,v)} + \underbrace{\sum_{T \in \mathcal{T}_h} \int_T \lambda^n (\nabla u \cdot \mathbf{n}_T)(\nabla v \cdot \mathbf{n}_T)}_{=j_h(u,v)}$$

For $\lambda^n \gtrsim h$ there holds

$$\|u_h\|_{\Gamma}^2 + j_h(u_h, u_h) \gtrsim h^{-1} \|u_h\|_{N_h}^2, \quad u_h \in \mathbb{P}_{\text{cont}}^k(\mathcal{T}_h)$$

\rightsquigarrow For $h^{-1} \gtrsim \lambda^n$: optimal error and condition number bounds independent of cut position.



J. Grande, C. Lehrenfeld, A. Reusken.

Analysis of a high-order trace finite element method for PDEs on level set surfaces.

SINUM 56(1):228–255, 2018.

Interior penalty Trace DG on irregular cut surface mesh

$$a_h(u, v) \rightsquigarrow \sum_{K \in \mathcal{K}_h} \int_K \nabla_{\Gamma_h} u \cdot \nabla_{\Gamma_h} v - \sum_{E \in \mathcal{E}_h} \int_E \{n_E \cdot \nabla u\} [v] - \sum_{E \in \mathcal{E}_h} \int_E \{n_E \cdot \nabla v\} [u] + \frac{\lambda}{h} \sum_{E \in \mathcal{E}_h} \int_E [u][v]$$

Stability issues:

- λ scales with shape regularity that may become **unbounded**.

¹not all volume d.o.f.s needed this time

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Remedy: Add stabilisations:

- Normal gradient volume stabilisation (as before):

$$j_h(u, v) = \sum_{T \in \mathcal{T}_h} \int_T \lambda^n (\nabla u \cdot \mathbf{n}_T) (\nabla v \cdot \mathbf{n}_T),$$

- Borrow stability from neighbouring **volume elements**¹.

$$\text{🤩}_h(u, v) = \sum_{F \in \mathcal{F}_h} \int_F \frac{\lambda_0^{\text{🤩}}}{h^2} [u][v] + \int_F \lambda_1^{\text{🤩}} [n_F \cdot \nabla u][n_F \cdot \nabla v]$$

¹not all volume d.o.f.s needed this time

Interior penalty Trace DG on irregular cut surface mesh

$$a_h(u, v) \rightsquigarrow \sum_{K \in \mathcal{K}_h} \int_K \nabla_{\Gamma_h} u \cdot \nabla_{\Gamma_h} v - \sum_{E \in \mathcal{E}_h} \int_E \{n_E \cdot \nabla u\} [v] - \sum_{E \in \mathcal{E}_h} \int_E \{n_E \cdot \nabla v\} [u] + \frac{\lambda}{h} \sum_{E \in \mathcal{E}_h} \int_E [u][v]$$

Stability issues:

- λ scales with shape regularity that may become **unbounded**.

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Trace DG analysis / Trefftz Trace DG


For $\lambda^n \simeq h^{-1}$, $\lambda_0^{\text{red}}, \lambda_1^{\text{red}} \gtrsim 1$ optimal error and condition number bounds indep. of cut position.

$$\lambda^n \rightarrow \infty \rightsquigarrow u_h \in \ker(j_h) = \{v \in \mathbb{P}^k(\mathcal{T}_h) \mid \nabla v \cdot \mathbf{n}_\Gamma = 0\} \leftarrow \text{Trefftz DG space}$$

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Analysis of TraceFEM reveals:

- It suffices to use $\mathbf{n}_h = \mathbf{n}_\Gamma + \mathcal{O}(h)$ in $j_h(\cdot, \cdot)$ for stability.
- It also suffices to penalize $\Pi^Q \mathbf{n}_h \cdot \nabla u$ in $j_h(\cdot, \cdot)$ for stability with $Q = \mathbb{P}^{k-1}(\mathcal{T}_h)$.

Modified Trace DG \rightsquigarrow Trace Trefftz DG

Relaxed normal gradient stabilization:

$$j_h^*(\lambda^n; u, v) = \sum_{T \in \mathcal{T}_h} \int_T \lambda^n (\Pi^Q \nabla u \cdot \mathbf{n}_T) (\Pi^Q \nabla v \cdot \mathbf{n}_T), \quad \rightsquigarrow \ker(j_h) = \{v \in \mathbb{P}^k(\mathcal{T}_h) \mid \Pi^Q \nabla v \cdot \mathbf{n}_T = 0\}$$

Then, the following three formulations are equivalent:

1

$u_h^1 := \lim_{\lambda^n \rightarrow \infty} u_\lambda^1$ with
Find $u_\lambda^1 \in \mathbb{P}^k(\mathcal{T}_h)$ s.t.

$$a_h(u_\lambda^1, v_h) + j_h^*(\lambda^n; u_\lambda^1, v_h) = f_h(v_h)$$

for all $v_h \in \mathbb{P}^k(\mathcal{T}_h)$.

2

Find $u_h^2, p_h^2 \in \mathbb{P}^k(\mathcal{T}_h) \times \mathbb{P}^{k-1}(\mathcal{T}_h)$ s.t.

$$a_h(u_h^2, v_h) + b_h(v_h, p_h^2) = f_h(v_h),$$

$$b_h(u_h^2, q_h) = 0,$$

for all $v_h, q_h \in \mathbb{P}^k(\mathcal{T}_h) \times \mathbb{P}^{k-1}(\mathcal{T}_h)$,
 $b_h(u, q) = \sum_{T \in \mathcal{T}_h} \int_T \nabla u \cdot \mathbf{n}_T \cdot q$.

3

Find $u_h^3 \in \ker(j_h^*)$ s.t.

$$a_h(u_h^3, v_h) = f_h(v_h)$$

for all $v_h \in \ker(j_h^*)$.

Analysis, Dimension reduction, implementation

Analysis of **1** and equivalence of **1**, **2**, **3** yields quasi best approximation results:

$$\|u - u_h\|_{1,\Gamma,h} \lesssim \inf_{v_h \in \ker(j_h^*)} \|u - v_h\|_{1,\Gamma,h}$$

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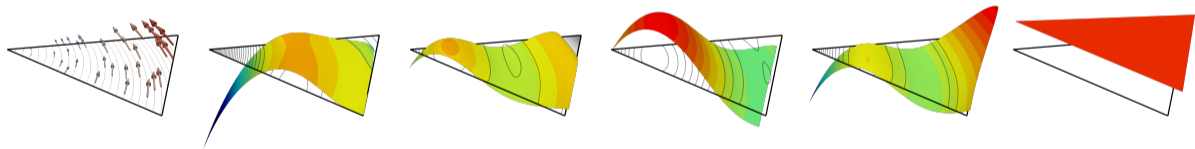
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E. Schlesinger,

Embedded Trefftz Trace DG Methods for PDEs on unfitted Surfaces.

Master's thesis, University of Göttingen, 2023.



Summary & Outlook

Unfitted Trefftz DG for elliptic PDEs

- 👻 penalty stabilisation **harmonizes well with Trefftz DG** (but not with Hybrid DG)
- 👉 **Embedded** Trefftz DG and **aggregated** FEM/DG are similar in virtue
- 🤔 impose other conditions (interface / boundary) into space generically?



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- 🔮 Reduce dimension of FESpace to surface dimension (3D \rightarrow 2D, 2D \rightarrow 1D)
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(possibly with relaxations to avoid locking 🗝)
- 😞 Vector-Laplace/Stokes: $-\mathcal{L}_{\Gamma} v = 0$, $\mathbf{n}_{\Gamma} \cdot \nabla v = 0$ and $v \cdot \mathbf{n}_{\Gamma} = 0$ in one Trefftz space?
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Thank you for your attention!